# ON A QUATERNIONIC FORM OF THE MAXWELL EQUATIONS FOR THE TIME-DEPENDENT ELECTROMAGNETIC FIELDS IN CHIRAL MEDIA

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April 11, 2003

### 1 Maxwell's equations for chiral media

In [2] a quaternionic reformulation of the time-harmonic Maxwell equations for chiral media was proposed and used in [4] in order to construct complete systems of quaternionic fundamental solutions convenient for numerical analysis of scattering boundary value problems. In the present contribution we give a quaternionic reformulation of time-dependent Maxwell's equations for chiral media. The Maxwell system is written as a single quaternionic equation. We obtain a fundamental solution of this equation and use it for solving Maxwell's system with sources.

Consider time-dependent Maxwell's equations with sources

$$\operatorname{rot} \overset{!}{E}(t;x) = i @_{t} \overset{!}{B}(t;x);$$

$$\operatorname{rot} \overset{1}{H}(t; \mathbf{x}) = \mathbf{@}_{t} \overset{1}{D}(t; \mathbf{x}) + \overset{1}{J}(t; \mathbf{x});$$

$$\operatorname{div} \overset{1}{E}(t; \mathbf{x}) = \frac{\frac{1}{N}(t; \mathbf{x})}{1}; \qquad \operatorname{div} \overset{1}{H}(t; \mathbf{x}) = 0 \tag{1}$$

and the constitutive relations of Drude-Born-Fedorov corresponding to the chiral media (see, e.g., [7], [8], [9])

$$\dot{B}(t; x) = {}^{1}(\dot{H}(t; x) + {}^{-}\operatorname{rot}\dot{H}(t; x));$$

$$\dot{D}(t; x) = {}^{"}(\dot{E}(t; x) + {}^{-}\operatorname{rot}\dot{E}(t; x));$$
(2)

here  $\bar{\ }$  is the chirality measure of the medium.  $\bar{\ }$ ; "; 1 are real constants.

We use also the Maxwell system with incorporated constitutive relations (2)

$$\operatorname{rot} \overset{1}{H}(t;x) = "(@_{t}\overset{1}{E}(t;x) + ^{-}@_{t}\operatorname{rot}\overset{1}{E}(t;x)) + \overset{1}{J}(t;x); \tag{3}$$

$$\operatorname{rot} \stackrel{!}{E}(t; \mathbf{x}) = i^{-1} (@_{t} \stackrel{!}{H}(t; \mathbf{x}) + {}^{-} @_{t} \operatorname{rot} \stackrel{!}{H}(t; \mathbf{x})): \tag{4}$$

Separating E and H we obtain the equations which represent analogues of the wave equations for non-chiral media

$$\begin{array}{l} \operatorname{rot}\operatorname{rot}\overset{1}{E}(x) + \text{"1@}_{t}^{2}\overset{1}{E}(x) + 2^{-\text{"1@}_{t}^{2}}\operatorname{rot}\overset{1}{E}(x) + \text{-2"1@}_{t}^{2}\operatorname{rot}\operatorname{rot}\overset{1}{E}(x) \\ = i \text{ "0}_{t}\overset{1}{J}(x) i \text{ "1@}_{t}\operatorname{rot}\overset{1}{J}(x); \end{array}$$

$$\operatorname{rot}\operatorname{rot}\overset{1}{H}(x) + \text{"1@}_{t}^{2}\overset{1}{H}(x) + 2^{-\text{"1}}\text{@}_{t}^{2}\operatorname{rot}\overset{1}{H}(x) + \text{-2"1}\text{@}_{t}^{2}\operatorname{rot}\operatorname{rot}\overset{1}{H}(x) = \operatorname{rot}\overset{1}{J}(x) : \tag{5}$$

It should be noted that when  $\bar{\ }=0$ , (5) reduce to the wave equations for non-chiral media.

## 2 Some notations from quaternionic analysis

We will consider biquaternion-valued functions defined in some domain  $\Omega$  ½  $R^3$ : On the set of continuously di¤erentiable such functions the well known Moisil-Teodoresco operator is defined by the expression  $D:=i_1\frac{@}{@x_1}+i_2\frac{@}{@x_2}+i_3\frac{@}{@x_3}$  (see, e.g., [1]). Denote  $D_{\$}:=D+\$$ , where \$ 2 C. The fundamental solution for this operator is known [5] (see also [6]):

$$\mathsf{K}_{\$}(x) = \mathsf{\; | \; } \operatorname{grad} \Theta_{\$}(x) + {\$}\Theta_{\$}(x) = ({\$} + \frac{x}{\mathsf{j}x\mathsf{j}^2} \; \mathsf{\; | \; } \mathsf{i}^{\$} \frac{x}{\mathsf{j}x\mathsf{j}})\Theta_{\$}(x); \tag{6}$$

 $x=\displaystyle {P_3\over k=1}\,x_k i_k .$  We assume that  ${\rm Im}\,^{\circledR}$   $\,$  0; and the fundamental solution  $\Theta_{\circledR}(x)$  of the Helmholtz operator is chosen as follows

$$\Theta_{\text{\tiny ®}}(x) = \frac{e^{i \text{\tiny ®} j x j}}{4 \text{\tiny $\frac{1}{4}$} j x j}.$$

# 3 Field equations in quaternionic form

In this section we rewrite the field equations from Section 1 in quaternionic form.

Let us introduce the following quaternionic operator

$$A := {}^{-}P_{\pi T} @_{t} D + {}^{P_{\pi T}} @_{t-1} iD$$
 (7)

and consider the purely vectorial biquaternionic function

$$V(t;x) = \stackrel{\stackrel{i}{\vdash}}{\vdash} (t;x) ; i \stackrel{\stackrel{1}{\vdash}}{=} \stackrel{i}{\vdash} (t;x):$$

The quaternionic equation

$$AV(t;x) = \frac{\Gamma_{\frac{1}{n}} \dot{J}}{\dot{J}}(t;x) + i \frac{h(t;x)}{n}$$
 (8)

has the scalar and the vector parts in the form:

$$i^{-p_{\text{TT}_{@_t}}} \operatorname{div} \overset{\text{i. }}{\stackrel{\text{...}}{=}} (t;x) + \frac{r_{\frac{1}{1}}}{\stackrel{\text{...}}{=}} \operatorname{div} \overset{\text{i. }}{\stackrel{\text{...}}{=}} (t;x) +$$

$$\begin{split} i(\operatorname{div}\overset{i}{E}(t;x) + {}^{-1} & @_{t}\operatorname{div}\overset{i}{H}(t;x)) = i\frac{{}^{h}(t;x)}{"}; \\ P_{\text{TT}} & & r_{\text{T}} \\ e_{t}\operatorname{rot}\overset{i}{E}(t;x) + P_{\text{TT}} & \overset{i}{E}(t;x) \\ & i & \text{Trot}\overset{i}{H}(t;x) \end{split}; \tag{9}$$

$$i \operatorname{rot} \overset{!}{E}(t; x) + {}^{-1} \mathscr{Q}_{t} \operatorname{rot} \overset{!}{H}(t; x) + {}^{1} \mathscr{Q}_{t} \overset{!}{H}(t; x)) = \overset{\Gamma}{-} \overset{!}{-} \overset{!}{J}(t; x): \tag{10}$$

The real part of (10) coincides with (3) and the imaginary part coincides with (4). Applying divergence to the equations (3) and (4) gives us

$$\mathbf{e}_t \operatorname{div} \mathbf{H}(t; \mathbf{x}) = 0$$
 and  $\mathbf{e}_t \operatorname{div} \mathbf{E}(t; \mathbf{x}) = 0$ :

Taking into account the last two equalities we obtain from (9) that the vectors E and H satisfy the equation (1).

Thus the quaternionic equation (8) is equivalent to the Maxwell system (1), (3) and (4).

It should be noted that for  $\bar{}=0$  from (7) we obtain the operator which was studied in [3] with the aid of the factorization of the wave operator for non-chiral media

$$\text{"1@}_t^2 \text{ i } \Delta_x = (\overset{D_{\text{TT}}}{}_{\text{e}_t} + \text{iD})(\overset{D_{\text{TT}}}{}_{\text{e}_t} \text{ i iD}) :$$

In the case under consideration we obtain a similar result. Let us denote by  $A^{\pi}$  the complex conjugate operator of A

$$\mathsf{A}^\mathtt{m} := {}^{-} P_{\texttt{mT} @_t} \mathsf{D} + {}^{} P_{\texttt{mT} @_t} + i \mathsf{D}$$

For simplicity we consider now a sourceless situation. In this case the equations (5) are homogeneous and can be represented as follows

$$\mathsf{A}\mathsf{A}^{\mathtt{x}}\,\dot{\boldsymbol{\mathsf{U}}}\,(\mathsf{t};\mathsf{x})=0;$$

where U stands for E or for H.

# 4 The fundamental solution for the operator A

We construct the fundamental solution for the operator A using the results of the previous section and well known facts from quaternionic analysis. Consider the following equation

$$Af(t;x)=({}^{-}{}^{D_{\textbf{m}}}\textbf{1}_{@_{t}}D+{}^{D_{\textbf{m}}}\textbf{1}_{@_{t}}\text{ }iD)f(t;x)={}^{\underline{\star}}(t){}^{\underline{\star}}(x){}:$$

Applying the Fourier transform F with respect to the time-variable t we arrive at

$$({}^-P_{{}^{\blacksquare} {}^{\blacksquare}}i \,! \, D + {}^D{}_{{}^{\blacksquare} {}^{\blacksquare}}i \,! \ \ _i \ iD) F (w; x) = {\pm}(x);$$

where F(w; x) = Fff(t; x)g: The last equation can be rewritten as follows

$$(D+{}^{\circledR})({}^{-}{}^{\raisebox{-1pt}{$D$}}{}_{^{\blacksquare}}\underline{{}}^{!} \ \ {}_{i} \ \ 1)iF(w;x)={\scriptstyle \pm}(x);$$

where  $^{\circledR}=\frac{P_{^{\blacksquare}\Gamma_!}}{^{^{\blacksquare}P^{\blacksquare}\Gamma_!}1}$  . The fundamental solution of  $D_{@}$  is given by (6), so we have

$$({}^{-}P_{^{\overline{w}}\underline{\tau}}! \text{ } i \text{ } 1)iF(w;x) = \text{ } i \text{ } \operatorname{grad} \Theta_{@}(x) + {}^{@}\Theta_{@}(x) = ({}^{@} + \frac{x}{jxj^{2}} \text{ } i \text{ } i^{@}\frac{x}{jxj})\Theta_{@}(x);$$

from where

$$F(w;x) = \frac{i^{p_{m_T}}!}{(-p_{m_T}! + 1)^2} \frac{\mu}{1 + \frac{ix}{jxj}} + \frac{ix}{jxj^2} \frac{1}{-p_{m_T}! + 1} \frac{e^{ijxj\frac{p_{m_T}}{p_{m_T}}}}{4\% jxj}$$

Applying the inverse Fourier transform we obtain the fundamental solution of the operator A:

Acknowledgement 1 This work was supported by CONACYT, project 32424-E.

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